



FIG. 8.6

neighborhood of $\alpha_i(t_0)$. Note that $\alpha_i[t_0, t_0 + \varepsilon]$ cannot be reparametrized to be geodesic. Thus by the uniqueness feature of Theorem 1.8, the radial geodesic segment σ from $\alpha_i(t_0)$ to $\alpha_i(t_0 + \varepsilon)$ is strictly shorter (Fig. 8.6). Replacing $\alpha_i[t_0, t_0 + \varepsilon]$ by σ changes α to a strictly shorter curve from \mathbf{p} to \mathbf{q} , contradicting the assumption that α is shortest. Thus α is a possibly broken geodesic.

Now we assume that α actually has a corner, say at $\alpha_{i-1}(b_i) = \alpha_i(b_i)$, and again deduce a contradiction. By the remark preceding this lemma, there is an $\varepsilon > 0$ such that $\alpha_{i-1}(b_i)$ is contained in a normal neighborhood \mathcal{N} of $\alpha_{i-1}(b_i - \varepsilon)$. By continuity, some initial subsegment $\alpha_i|_{[b_i, t_1]}$ of α_i is still in \mathcal{N} .

Thus the combined curve from $\alpha_{i-1}(b_i - \varepsilon)$ to $\alpha_i(t_1)$ has a corner and lies in \mathcal{N} . So it is strictly longer than the radial geodesic τ of \mathcal{N} joining these points (Fig. 8.6). Then as before, replacing the combined curve by τ shortens α , giving the required contradiction. \blacklozenge

Exercises

1. Prove:

- A normal ε -neighborhood of \mathbf{p} in M consists of all points \mathbf{q} in M such that $\rho(\mathbf{p}, \mathbf{q}) < \varepsilon$.
- If $\mathbf{p} \neq \mathbf{q}$ in M , then $\rho(\mathbf{p}, \mathbf{q}) > 0$. (This completes the proof that intrinsic distance ρ is a metric on M ; see Ex. 3 of Sec. 6.4.)

2. (Normal coordinates.) Let $\mathcal{N} = \exp_p(\mathcal{U})$ be a normal neighborhood of a point \mathbf{p} in M , and let $\mathbf{e}_1, \mathbf{e}_2$ be a frame at \mathbf{p} . Prove:

- The mapping

$$\mathbf{n}(x, y) = \exp_p(x\mathbf{e}_1 + y\mathbf{e}_2)$$

is a coordinate patch on \mathcal{N} .

- At \mathbf{p} (but generally not elsewhere) $E = 1, F = 0, G = 1$. Thus normal coordinates are Euclidean at \mathbf{p} , hence at least approximately Euclidean near \mathbf{p} .
- Coordinate straight lines through \mathbf{p} are geodesics of M .

- (d) With suitable choices, \mathbf{n} for \mathbf{R}^2 is the identity map $\mathbf{n}(x, y) = (x, y)$. So for arbitrary M , normal coordinates generalize the natural (rectangular) coordinates of \mathbf{R}^2 .
3. At the point $\mathbf{p} = (r, 0, 0)$ of the cylinder $M: x^2 + y^2 = r^2$, let $\mathbf{e}_1 = (0, 1, 0)$ and $\mathbf{e}_2 = (0, 0, 1)$. Find an explicit formula for the normal parametrization in Exercise 2. What is the largest normal neighborhood of the point \mathbf{p} ?
4. (*Continuation.*) Prove:
- (a) A geodesic starting at an arbitrary point $\mathbf{p} = (a, b, c)$ in the cylinder M does not minimize arc length after it passes through the antipodal line $t \rightarrow (-a, -b, t)$. (Only vertical geodesics through \mathbf{p} fail to meet this line.)
 - (b) If \mathbf{q} is not on the antipodal line of \mathbf{p} , there is a unique shortest geodesic from \mathbf{p} to \mathbf{q} .
 - (c) Derive a formula for intrinsic distance on the cylinder.
5. Let M be an augmented surface of revolution (Ex. 12 of Sec. 4.1). Prove, without computation:
- (a) If M has only one intercept \mathbf{p} on the axis of revolution, then every geodesic segment γ starting at \mathbf{p} uniquely minimizes arc length.
 - (b) If M has a second intercept \mathbf{q} , then the conclusion in (a) holds if and only if γ does not reach \mathbf{q} .
6. In M let α be a curve segment in M from \mathbf{p} to \mathbf{q} , and β a curve segment from \mathbf{q} to \mathbf{r} . Joining α and β does not usually produce a differentiable curve from \mathbf{p} to \mathbf{r} since $\alpha + \beta$ will usually have a corner at \mathbf{q} .

In this case, prove that there is a piecewise smooth curve γ from \mathbf{p} to \mathbf{r} that is arbitrarily close to $\alpha + \beta$ but strictly shorter: $L(\gamma) < L(\alpha) + L(\beta)$. (*Hint:* See proof of Cor. 1.10.)

Techniques from advanced calculus show that the corner can actually be smoothed away, leaving γ differentiable throughout.

7. (*Intrinsic distance is continuous.*)
- (a) For \mathbf{p}_0 in M , show that the real-valued function $\mathbf{p} \rightarrow \rho(\mathbf{p}_0, \mathbf{p})$ is continuous; in fact, if $\rho(\mathbf{p}, \mathbf{q}) < \varepsilon$, then $|\rho(\mathbf{p}_0, \mathbf{p}) - \rho(\mathbf{p}_0, \mathbf{q})| < \varepsilon$.
 - (b) State precisely and prove that the function $(\mathbf{p}, \mathbf{q}) \rightarrow \rho(\mathbf{p}, \mathbf{q})$ is continuous.
8. The radial geodesics from the point $(0, 1)$ in the Poincaré half-plane P are given by $(x - a)^2 + y^2 = a^2 + 1$ for all a (see Ex. 1 of Sec. 7.5).
- (a) Show that the curves given by $x^2 + (y - b)^2 = b^2 - 1$ for all $b > 1$ are everywhere orthogonal to these geodesics.
 - (b) Deduce that the curves in (a) are the polar circles about the pole $(0, 1)$.
 - (c) (*Computer graphics.*) Plot a few curves from each family on the same figure.